

Duality in vv-RKHSs with Infinite Dimensional Outputs: Application to Robust Losses

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Motivations

A duality theory for general OVks

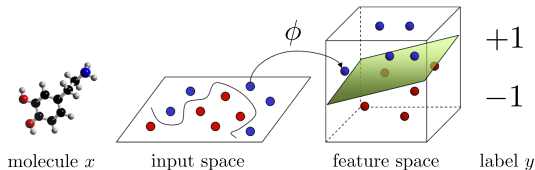
Robust losses as convolutions

Experiments

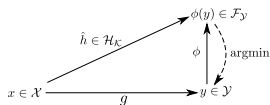
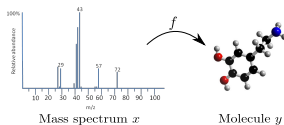
Conclusion

Motivation 1: structured prediction by surrogate approach

Kernel trick in the input space.

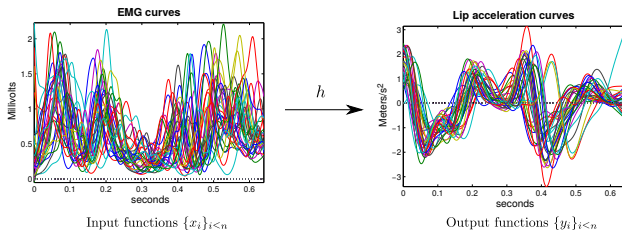


Kernel trick in the output space [Cortes '05, Geurts '06, Brouard '11, Kadri '13, Brouard '16], **Input Output Kernel Regression (IOKR)**.



$$\hat{h} = \underset{h \in \mathcal{H}_K}{\text{argmin}} \frac{1}{2n} \sum_{i=1}^n \left\| \phi(y_i) - h(x_i) \right\|_{\mathcal{F}_Y}^2 + \frac{\Lambda}{2} \|h\|_{\mathcal{H}_K}^2, \quad g(x) = \underset{y \in \mathcal{Y}}{\text{argmin}} \left\| \phi(y) - \hat{h}(x) \right\|_{\mathcal{F}_Y}$$

Motivation 2: function to function regression



$$\min_{h \in \mathcal{H}_{\mathcal{K}}} \frac{1}{2n} \sum_{i=1}^n \|y_i - h(x_i)\|_{L_2}^2 + \frac{\Lambda}{2} \|h\|^2 \quad [\text{Kadri et al., 2016}]$$

And many more!

e.g. *structured data autoencoding* [Laforgue et al., 2019]

$$\min_{h_1, h_2 \in \mathcal{H}_{\mathcal{K}}^1 \times \mathcal{H}_{\mathcal{K}}^2} \frac{1}{2n} \sum_{i=1}^n \|\phi(x_i) - h_2 \circ h_1(\phi(x_i))\|_{\mathcal{F}_{\mathcal{X}}}^2 + \Lambda \text{Reg}(h_1, h_2).$$

Question: Is it possible to extend the previous approaches to different (ideally robust) loss functions?

First answer: Yes, possible extension to maximum-margin regression [Brouard et al., 2016], and ϵ -insensitive loss functions for matrix-valued kernels [Sangnier et al., 2017]

What about general Operator-Valued Kernels (OVKs)?

What about other types of loss functions?

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Learning in vector-valued RKHSs (vv-RKHSs)

- $\mathcal{K}: \mathcal{X} \times \mathcal{X} \rightarrow \mathcal{L}(\mathcal{Y})$, $\mathcal{K}(x, x') = \mathcal{K}(x', x)^*$, $\sum_{i,j} \langle y_i, \mathcal{K}(x_i, x_j) y_j \rangle_{\mathcal{Y}} \geq 0$
- Unique vv-RKHS $\mathcal{H}_{\mathcal{K}} \subset \mathcal{F}(\mathcal{X}, \mathcal{Y})$, $\mathcal{H}_{\mathcal{K}} = \overline{\text{Span} \{ \mathcal{K}(\cdot, x) y : x, y \in \mathcal{X} \times \mathcal{Y} \}}$
- **Ex:** decomposable OVK $\mathcal{K}(x, x') = k(x, x')A$, with k scalar, A p.s.d. on \mathcal{Y}

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- Ex: decomposable OVK $\mathcal{K}(x, x') = k(x, x')A$, with k scalar, A p.s.d. on \mathcal{Y}
- For $\{(x_i, y_i)\}_{i=1}^n \in (\mathcal{X} \times \mathcal{Y})^n$ with \mathcal{Y} a Hilbert space, we want to find:

$$\hat{h} \in \underset{h \in \mathcal{H}_{\mathcal{K}}}{\text{argmin}} \frac{1}{n} \sum_{i=1}^n \ell(h(x_i), y_i) + \frac{\Lambda}{2} \|h\|_{\mathcal{H}_{\mathcal{K}}}^2.$$

Representer Theorem [Micchelli and Pontil, 2005]:

$$\exists (\hat{\alpha}_i)_{i=1}^n \in \mathcal{Y}^n \text{ (infinite dimensional!)} \quad \text{s.t.} \quad \hat{h}(x) = \sum_{i=1}^n \mathcal{K}(\cdot, x_i) \hat{\alpha}_i.$$

When $\ell(\cdot, \cdot) = \frac{1}{2} \|\cdot - \cdot\|_{\mathcal{Y}}^2$, $\mathcal{K} = k \cdot \mathbf{I}_{\mathcal{Y}}$: $\hat{\alpha}_i = \sum_{j=1}^n A_{ij} y_j$, $A = (K + n\Lambda \mathbf{I}_n)^{-1}$.

Applying duality

$$\hat{h} \in \operatorname{argmin}_{h \in \mathcal{H}_{\mathcal{K}}} \frac{1}{n} \sum_{i=1}^n \ell_i(h(x_i)) + \frac{\Lambda}{2} \|h\|_{\mathcal{H}_{\mathcal{K}}}^2 \quad \text{is given by} \quad \hat{h} = \frac{1}{\Lambda n} \sum_{i=1}^n \mathcal{K}(\cdot, x_i) \hat{\alpha}_i,$$

with $(\hat{\alpha}_i)_{i=1}^n \in \mathcal{Y}^n$ the solutions to the **dual problem**:

$$\min_{(\alpha_i)_{i=1}^n \in \mathcal{Y}^n} \sum_{i=1}^n \ell_i^*(-\alpha_i) + \frac{1}{2\Lambda n} \sum_{i,j=1}^n \langle \alpha_i, \mathcal{K}(x_i, x_j) \alpha_j \rangle_{\mathcal{Y}},$$

with $f^* : \alpha \in \mathcal{Y} \mapsto \sup_{y \in \mathcal{Y}} \langle \alpha, y \rangle_{\mathcal{Y}} - f(y)$ the Fenchel-Legendre transform of f .

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- **1st limitation:** the FL transform ℓ^* needs to be computable (\rightarrow assumption)
- **2nd limitation :** the dual variables $(\alpha_i)_{i=1}^n$ are still **infinite dimensional!**

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- **1st limitation:** the FL transform ℓ^* needs to be computable (\rightarrow assumption)
- **2nd limitation :** the dual variables $(\alpha_i)_{i=1}^n$ are still **infinite dimensional!**

If $\mathbf{Y} = \operatorname{Span}\{y_j, j \leq n\}$ invariant by \mathcal{K} , i.e. $\forall (x, x'), y \in \mathbf{Y} \Rightarrow \mathcal{K}(x, x')y \in \mathbf{Y}$:

then $\hat{\alpha}_i \in \mathbf{Y} \rightarrow$ possible reparametrization: $\hat{\alpha}_i = \sum_j \hat{\omega}_{ij} y_j$

The double representer theorem (1/2)

Assume that OVK \mathcal{K} and loss ℓ satisfy the appropriate assumptions (see paper for details, verified by standard kernels and losses), then

$\hat{h} = \operatorname{argmin}_{\mathcal{H}_{\mathcal{K}}} \frac{1}{n} \sum_i \ell(h(x_i), y_i) + \frac{\Lambda}{2} \|h\|_{\mathcal{H}_{\mathcal{K}}}^2$ is given by

$$\hat{h} = \frac{1}{\Lambda n} \sum_{i,j=1}^n \mathcal{K}(\cdot, x_i) \hat{\omega}_{ij} y_j,$$

with $\hat{\Omega} = [\hat{\omega}_{ij}] \in \mathbb{R}^{n \times n}$ the solution to the **finite dimensional** problem

$$\min_{\Omega \in \mathbb{R}^{n \times n}} \sum_{i=1}^n L_i(\Omega_{i:}, K^Y) + \frac{1}{2\Lambda n} \operatorname{Tr}(\tilde{M}^T(\Omega \otimes \Omega)),$$

with \tilde{M} the $n^2 \times n^2$ matrix writing of M s.t. $M_{ijkl} = \langle y_k, \mathcal{K}(x_i, x_j) y_l \rangle_{\mathcal{Y}}$.

The double representer theorem (2/2)

If \mathcal{K} further satisfies $\mathcal{K}(x, x') = \sum_t k_t(x, x')A_t$, then tensor M simplifies to $M_{ijkl} = \sum_t [K_t^X]_{ij}[K_t^Y]_{kl}$ and the problem rewrites

$$\min_{\Omega \in \mathbb{R}^{n \times n}} \sum_{i=1}^n L_i(\Omega_{i:}, K^Y) + \frac{1}{2\Lambda n} \sum_{t=1}^T \text{Tr}(K_t^X \Omega K_t^Y \Omega^T).$$

Rmk. Only need the n^4 tensor $\langle y_k, \mathcal{K}(x_i, x_j) y_l \rangle_y$ to learn OVKMs.

Simplifies to 2 n^2 matrices $K_{ij}^X K_{kl}^Y$ if \mathcal{K} is decomposable.

How to apply the duality approach?

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Infimal convolution and Fenchel-Legendre transforms

Infimal-convolution operator \square between proper lower semicontinuous functions [Bauschke et al., 2011]:

$$(f \square g)(x) = \inf_y f(y) + g(x - y).$$

Relation to FL transform:

$$(f \square g)^* = f^* + g^*$$

Ex: ϵ -insensitive losses. Let $\ell : \mathcal{Y} \rightarrow \mathbb{R}$ be a convex loss with unique minimum at 0, and $\epsilon > 0$. The ϵ -insensitive version of ℓ , denoted ℓ_ϵ , is defined by:

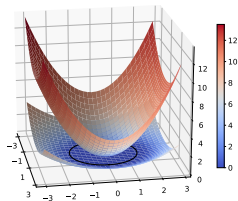
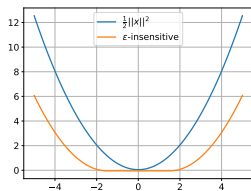
$$\ell_\epsilon(y) = (\ell \square \chi_{\mathcal{B}_\epsilon})(y) = \begin{cases} \ell(0) & \text{if } \|y\|_{\mathcal{Y}} \leq \epsilon \\ \inf_{\|d\|_{\mathcal{Y}} \leq 1} \ell(y - \epsilon d) & \text{otherwise} \end{cases},$$

and has FL transform:

$$\ell_\epsilon^*(y) = (\ell \square \chi_{\mathcal{B}_\epsilon})^*(y) = \ell^*(y) + \epsilon \|y\|.$$

Interesting loss functions: sparsity and robustness

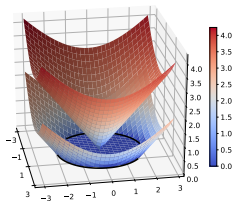
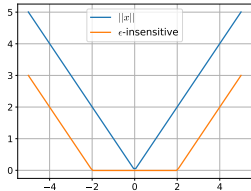
ϵ -Ridge



$$\frac{1}{2}\| \cdot \|^2 \square \chi_{\mathcal{B}_\epsilon}$$

(Sparsity)

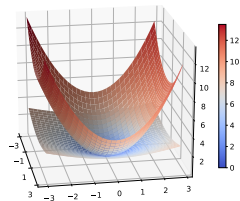
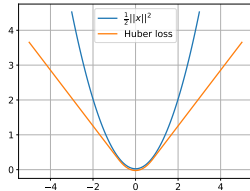
ϵ -SVR



$$\| \cdot \| \square \chi_{\mathcal{B}_\epsilon}$$

(Sparsity, Robustness)

κ -Huber



$$\kappa \| \cdot \| \square \frac{1}{2} \| \cdot \|^2$$

(Robustness)

For the ϵ -ridge, ϵ -SVR and κ -Huber, it holds $\hat{\Omega} = \hat{W}V^{-1}$, with \hat{W} the solution to these finite dimensional dual problems:

$$(D1) \quad \min_{W \in \mathbb{R}^{n \times n}} \quad \frac{1}{2} \|AW - B\|_{\text{Fro}}^2 + \epsilon \|W\|_{2,1},$$

$$(D2) \quad \min_{W \in \mathbb{R}^{n \times n}} \quad \frac{1}{2} \|AW - B\|_{\text{Fro}}^2 + \epsilon \|W\|_{2,1},$$

s.t. $\|W\|_{2,\infty} \leq 1,$

$$(D3) \quad \min_{W \in \mathbb{R}^{n \times n}} \quad \frac{1}{2} \|AW - B\|_{\text{Fro}}^2,$$

s.t. $\|W\|_{2,\infty} \leq \kappa,$

with V, A, B such that: $VV^T = K^Y$, $A^T A = K^X / (\Lambda n) + \mathbf{I}_n$
(or $A^T A = K^X / (\Lambda n)$ for the ϵ -SVR), and $A^T B = V$.

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Surrogate approaches for structured prediction

- Experiments on YEAST dataset
- Empirically, ϵ -SV-IOKR outperforms ridge-IOKR for a wide range of ϵ
- Promotes sparsity and acts as a regularizer

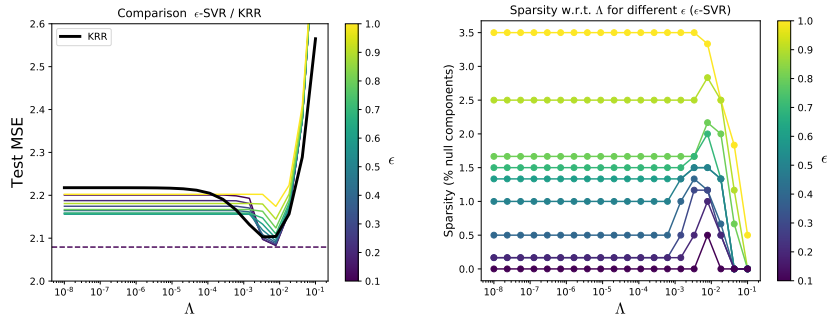


Figure 1: MSEs and sparsity w.r.t. Λ for several ϵ

Robust function-to-function regression

Task from [Kadri et al., 2016]: predict lip acceleration from EMG signals.

- Dataset augmented with outliers, model learned with Huber loss
- Improvement for every output size M (see paper for approximation)

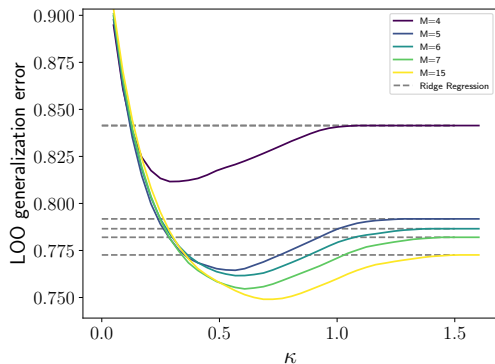


Figure 2: LOO generalization error w.r.t. κ

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State of the art:





- OVK and vv-RKHSs tailored to infinite dimensional outputs
- RT: expansion with few information on the coefficients
- Duality: coefficients solutions to the (infinite) dual problem

Contributions:

- Double RT: coefficients linear combinations of the outputs
- Allows to cope with many losses (ϵ , Huber) and kernels
- Empirical improvements on surrogate approaches

Much more in the paper!

- Thorough algorithmic stability analysis
- What if \mathbf{Y} is not invariant by \mathcal{K} ?

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On the invariance assumption

With $\mathbf{Y} = \text{Span}\{y_j, j \leq n\}$, the assumption reads:

$$\forall (x, x') \in \mathcal{X}^2, \forall y \in \mathcal{Y}, \quad y \in \mathbf{Y} \implies \mathcal{K}(x, x')y \in \mathbf{Y}$$

- We do not need it to hold for every collection of $\{y_i\}_{i \leq n} \in \mathcal{Y}^n$
- Rather an a posteriori condition to ensure that the kernel is *aligned*
- The little we know about \mathcal{Y} should be preserved through \mathcal{K}
- If \mathcal{Y} finite dimensional, and sufficiently many outputs, then $\mathbf{Y} = \mathcal{Y}$
- Identity-decomposable kernels fit (nontrivial in infinite dimension)
- The empirical covariance kernel $\sum_i y_i \otimes y_i$ [Kadri et al., 2013] fits

Admissible kernels

- $\mathcal{K}(s, t) = \sum_i k_i(s, t) y_i \otimes y_i$,
with k_i positive semi-definite (p.s.d.) scalar kernels for all $i \leq n$
- $\mathcal{K}(s, t) = \sum_i \mu_i k(s, t) y_i \otimes y_i$,
with k a p.s.d. scalar kernel and $\mu_i \geq 0$ for all $i \leq n$
- $\mathcal{K}(s, t) = \sum_i k(s, x_i)k(t, x_i) y_i \otimes y_i$,
- $\mathcal{K}(s, t) = \sum_{i,j} k_{ij}(s, t) (y_i + y_j) \otimes (y_i + y_j)$,
with k_{ij} p.s.d. scalar kernels for all $i, j \leq n$
- $\mathcal{K}(s, t) = \sum_{i,j} \mu_{ij} k(s, t) (y_i + y_j) \otimes (y_i + y_j)$,
with k a p.s.d. scalar kernel and $\mu_{ij} \geq 0$
- $\mathcal{K}(s, t) = \sum_{i,j} k(s, x_i, x_j)k(t, x_i, x_j) (y_i + y_j) \otimes (y_i + y_j)$.

$$\forall i \leq n, \forall (\alpha^{\mathbf{Y}}, \alpha^{\perp}) \in \mathbf{Y} \times \mathbf{Y}^{\perp}, \quad \ell_i^*(\alpha^{\mathbf{Y}}) \leq \ell_i^*(\alpha^{\mathbf{Y}} + \alpha^{\perp})$$

- $\ell_i(y) = f(\langle y, z_i \rangle)$, $z_i \in \mathbf{Y}$ and $f : \mathbb{R} \rightarrow \mathbb{R}$ convex. Maximum-margin obtained with $z_i = y_i$ and $f(t) = \max(0, 1 - t)$.
- $\ell(y) = f(\|y\|)$, $f : \mathbb{R}_+ \rightarrow \mathbb{R}$ convex increasing s.t. $t \mapsto \frac{f'(t)}{t}$ is continuous over \mathbb{R}_+ . Includes the functions $\frac{\lambda}{\eta} \|y\|^\eta$ for $\eta > 1$, $\lambda > 0$.
- $\forall \lambda > 0$, with \mathcal{B}_λ the centered ball of radius λ ,
 - ▶ $\ell(y) = \lambda \|y\|$,
 - ▶ $\ell(y) = \lambda \|y\| \log(\|y\|)$,
 - ▶ $\ell(y) = \chi_{\mathcal{B}_\lambda}(y)$,
 - ▶ $\ell(y) = \lambda(\exp(\|y\|) - 1)$.
- $\ell_i(y) = f(y - y_i)$, f^* verifying the condition.
- Infimal convolution of functions verifying the condition. (ϵ -insensitive [Sangnier et al., 2017], the Huber loss [Huber, 1964], Moreau or Pasch-Hausdorff envelopes [Moreau, 1962, Bauschke et al., 2011])

Dual problem:

$$(\hat{\alpha}_i)_{i=1}^n \in \underset{(\alpha_i)_{i=1}^n \in \mathcal{Y}^n}{\operatorname{argmin}} \sum_{i=1}^n \ell_i^*(-\alpha_i) + \frac{1}{2\Lambda n} \sum_{i,j=1}^n \langle \alpha_i, \mathcal{K}(x_i, x_j) \alpha_j \rangle_{\mathcal{Y}}.$$

- Decompose $\hat{\alpha}_i = \alpha_i^{\mathbf{Y}} + \alpha_i^{\perp}$, with $(\alpha_i^{\mathbf{Y}})_{i \leq n}, (\alpha_i^{\perp})_{i \leq n} \in \mathbf{Y}^n \times \mathbf{Y}^{\perp n}$
- Assume that $\ell_i^*(\alpha^{\mathbf{Y}}) \leq \ell_i^*(\alpha^{\mathbf{Y}} + \alpha^{\perp})$ (satisfied if ℓ relies on $\langle \cdot, \cdot \rangle$)

Then it holds:

$$\begin{aligned} & \sum_{i=1}^n \ell_i^*(-\alpha_i^{\mathbf{Y}}) + \frac{1}{2\Lambda n} \sum_{i,j=1}^n \langle \alpha_i^{\mathbf{Y}}, \mathcal{K}(x_i, x_j) \alpha_j^{\mathbf{Y}} \rangle_{\mathcal{Y}} \\ & \leq \sum_{i=1}^n \ell_i^*(-\alpha_i^{\mathbf{Y}} - \alpha_i^{\perp}) + \frac{1}{2\Lambda n} \sum_{i,j=1}^n \langle \alpha_i^{\mathbf{Y}} + \alpha_i^{\perp}, \mathcal{K}(x_i, x_j) (\alpha_j^{\mathbf{Y}} + \alpha_j^{\perp}) \rangle_{\mathcal{Y}}. \end{aligned}$$

Approximating the dual problem if no invariance

The kernel $\mathcal{K} = k \cdot A$ is a separable OVK, with A a compact operator.

There exists an o.n.b. $(\psi_j)_{j=1}^\infty$ of \mathcal{Y} , s.t. $A = \sum_{j=1}^\infty \lambda_j \psi_j \otimes \psi_j$, ($\lambda_j \geq 0$).

There exists $(\hat{\omega}_i)_{i=1}^n \in \ell^2(\mathbb{R})^n$ such that $\forall i \leq n$, $\hat{\alpha}_i = \sum_{j=1}^\infty \hat{\omega}_{ij} \psi_j$.

Denoting by $\tilde{\mathcal{Y}}_m = \text{span}(\{\psi_j\}_{j=1}^m)$, $S = \text{diag}(\lambda_j)_{j=1}^m$, solve instead:

$$\min_{(\alpha_i)_{i=1}^n \in \tilde{\mathcal{Y}}_m^n} \sum_{i=1}^n \ell_i^*(-\alpha_i) + \frac{1}{2\Lambda n} \sum_{i,j=1}^n \langle \alpha_i, \mathcal{K}(x_i, x_j) \alpha_j \rangle_{\mathcal{Y}}.$$

The final solution is given by: $\hat{h} = \frac{1}{\Lambda n} \sum_{i=1}^n \sum_{j=1}^m k(\cdot, x_i) \lambda_j \hat{\omega}_{ij} \psi_j$,

with $\hat{\Omega}$ solution to:

$$\min_{\Omega \in \mathbb{R}^{n \times m}} \sum_{i=1}^n L_i(\Omega_i, R_i) + \frac{1}{2\Lambda n} \text{Tr}(K^X \Omega S \Omega^T).$$

Application to kernel autoencoding

- Experiments on molecules with Tanimoto-Gaussian kernel
- Empirical improvements for wide range of ϵ
- Introduces sparsity

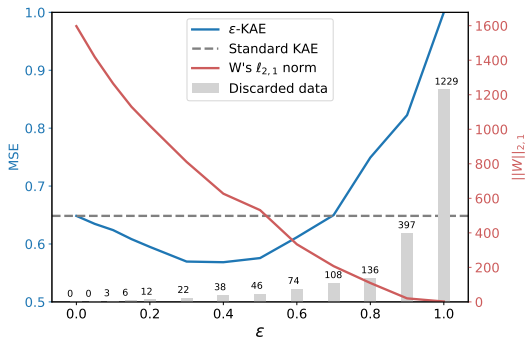


Figure 3: Performances of ϵ -insensitive Kernel Autoencoder

Algorithm A has stability β if for any sample S_n , and any $i \leq n$, it holds:

$$\sup_{(x,y) \in \mathcal{X} \times \mathcal{Y}} |\ell(h_{A(S_n)}(x), y) - \ell(h_{A(S_n \setminus i)}(x), y)| \leq \beta$$

Let A be an algorithm with stability β and loss function bounded by M . Then, for any $n \geq 1$ and $\delta \in]0, 1[$ it holds with probability at least $1 - \delta$:

$$\mathcal{R}(h_{A(S_n)}) \leq \hat{\mathcal{R}}_n(h_{A(S_n)}) + 2\beta + (4n\beta + M) \sqrt{\frac{\ln(1/\delta)}{2n}}.$$

If $\|\mathcal{K}(x, x)\|_{\text{op}} \leq \gamma^2$, and $|\ell(h_S(x), y) - \ell(h_{S \setminus i}(x), y)| \leq C \|h_S(x) - h_{S \setminus i}(x)\|_{\mathcal{Y}}$, then OVK algorithm has stability $\beta \leq C^2 \gamma^2 / (\Lambda n)$ [Audiffren and Kadri, 2013].

	M	C
ϵ -SVR	$\sqrt{M_{\mathcal{Y}} - \epsilon} \left(\frac{\sqrt{2}\gamma}{\sqrt{\Lambda}} + \sqrt{M_{\mathcal{Y}} - \epsilon} \right)$	1
ϵ -Ridge	$(M_{\mathcal{Y}} - \epsilon)^2 \left(1 + \frac{2\sqrt{2}\gamma}{\sqrt{\Lambda}} + \frac{2\gamma^2}{\Lambda} \right)$	$2(M_{\mathcal{Y}} - \epsilon) \left(1 + \frac{\gamma\sqrt{2}}{\sqrt{\Lambda}} \right)$
κ -Huber	$\kappa \sqrt{M_{\mathcal{Y}} - \frac{\kappa}{2}} \left(\frac{\gamma\sqrt{2\kappa}}{\sqrt{\Lambda}} + \sqrt{M_{\mathcal{Y}} - \frac{\kappa}{2}} \right)$	κ